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CORUS-XUAM 2nd Workshop

AURA PJ34 Overview

16th March 2022





AURA in a nutshell

- Objective:
 - To lay the foundations for the **integration of drones in current and future air traffic environment**, developing the required concept of operations and validating U-space services information exchange with ATM systems.
- Context:
 - Industrial Research project.
 - More than 25 partners, including ANSPs and ground and air industry.
 - Duration 30 months from January 2021 to June 2023.

Budget

11.4 M€



Solution 2 > Main characteristics

- Highly dynamic management of AUSA airspace, governed by ATC in controlled airspace.
- Assessment of DAC impact on manned and unmanned operations.
- High levels of automation in the ATM-U-space processes.
- Majority of autonomous or highly automated UAS operations.

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• Methods to manage contingency and nonnominal situations.



How we see the airspace? > First Scenario



How we see the airspace? > Second Scenario



An example > Operational Environment

- Medium-sized regional airport:
 - Single runway.

VUS

- Standard IFR and VFR operations.
- Emergency helicopter operations.
- Frequent routes protected through permanent segregation.
- Ratio of U-space flights to crewed flights 10:1.
- Vertiport for UAM in proximity.
- Management of AUSA airspace:
 - Most of the airspace reserved for U-space.
 - Pre-defined grid structure to enable ad-hoc operations (e.g. VFR flights or HEMS traffic).
 - Pre-defined UAS transfer corridors.
 - Single CISP and one or several USSPs.



An example > Responsibilities

- ATC in charge of their standard tasks ("business as usual").
- ATC controller or **Dynamic Airspace Reconfiguration Manager** (**DAR-M**) are in charge of DARs.
 - DAR is supported by predefined dynamic geo-fences which can be (de)activated in real-time by ATC.
- USSPs coordinate the approval of UAS operation plans.
 - No need of ATC approval of drone operations plans which are entirely in delegated AUSA airspace.
- Separation between UAVs is under the responsibility of USSPs or UAVs – autonomous or GCSs -.



ERATO

An example > Processes

- ATCO displays airspace management tool at 15:12.
 - Origin and CTR exit point ERATO -.
 - Geofencing request of 15 minutes starting ASAP.
- · What-if tool: Cells to be geofenced are automatically visualized.
- What-if tool: Quantification of **impact**:
 - Number of impacted high-priority and high-risk drone operations.
 - Cancelled missions.
 - Overall mission efficiency impact.
- What-if tool: Estimated exit time of all drones at 15:17.
 - Departure clearance estimation.





Other example > Towards seamless integration

- **Dynamic 4D airspace management**: Manned aircraft intruding U-space airspace.
 - Manned aircraft in AUSA airspace managed by ATC deviates from its cleared trajectory, which leads to a risk of penetrating U-space airspace.
 - U-space takes corective actions to resolve the situation, such that the segregation is sill ensured.





Thank you very much for your attention!



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